



IQS231A Datasheet

Single Channel Capacitive Proximity/Touch Controller for SAR applications

The IQS231A ProxSense® IC is a self-capacitance controller designed for applications where an awake/activate on proximity function is required. The IQS231A is an ultra-low power solution that uses unique release and/or movement detection for applications that require long-term detection. The IQS231A operates standalone or I2C and features configuration via OTP (One Time Programmable) bits. Switching from I2C to standalone during runtime is also possible in order to access all settings while offering the simplicity of a standalone output.

Features

- Integrated SAR user interface offering a simple GPIO output
- Quick release detection effectively prevent false triggers
- Quick release sensitivity options
- Wide range of control for sensing in high power RF environments
- Pin compatible with IQS128 and IQS229
- 1.8V to 3.3V Input voltage
- Capacitive resolution down to 0.02fF
- Capacitive load capability up to 200pF
- External threshold adjustment pin (minimize need for pre-empted OTP adjustments)
- Minimal external components (direct input strap)
- Standalone failsafe mode (backwards compatible failsafe output, short pulses on output to indicate operational device)
- Default OTP options focus on safety and passing SAR lab qualification, OTP changes offer performance advantages
- **I2C interface option** (improved compatibility)



- Extended controls in I²C mode (setup in I²C, runtime with standalone output)
- Optional input for synchronized implementations (input to instruct IC when to sense)
- Synchronization output failsafe pulses may be used by the master to synchronize on. Sensing is done after each pulse
- Synchronization input Sensing is only done while Sync input is low
- Low power sensing: 30Hz (default), 100Hz, 8Hz, 4Hz (sub 6uA mode)
- Constant sampling rates during all power modes with rapidly debounced output changes
- Advanced temperature & interference compensation option

Applications

- SAR sensor
- Integrated hybrid designs (RF and ocapacitive sensing combined)
- Movement sensing applications (user interaction detection, anti-theft)
- Hold detection for screen activation
- On-ear detection

| T _A | DFN-10 | TSOT23-6 | WLCSP-8 | | |
|----------------|---------|----------|---------|--|--|
| -20°C to 85°C | IQS231A | IQS231A | IQS231A | | |





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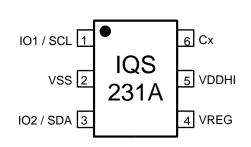


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1 Summary: Packaging and Pin-Out (TSOT23-6 & DFN10)



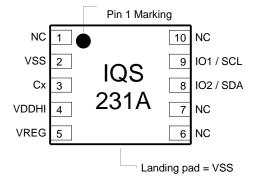


Figure 1.1 IQS231A TSOT23-6 pin-out

Figure 1.2 IQS231A DFN10 pin-out

Table 1.1 TSOT23-6 Pin-out description

| | IQS231A TSOT23-6 | | | | | | | |
|-----|------------------|----------------------|---|--|--|--|--|--|
| Pin | Name | Function | | | | | | |
| 1 | PRIMARY I/O | Digital Input/Output | Multifunction IO1 / SCL (I ² C Clock signal) | | | | | |
| 2 | VSS | Signal GND | | | | | | |
| 3 | SECONDARY I/O | Digital Input/Output | Multifunction IO2 / SDA (I ² C Data output) | | | | | |
| 4 | VREG | Regulator output | Requires external capacitor | | | | | |
| 5 | VDDHI | Supply Input | Supply:1.8V – 3.3V | | | | | |
| 6 | Сх | Sense electrode | Connect to conductive area intended for sensor | | | | | |

Table 1.2 DFN10 Pin-out description

| | IQS231A DFN10 | | | | | | | |
|-----|---------------|----------------------|---|--|--|--|--|--|
| Pin | Name | Туре | Function | | | | | |
| 1 | NC | | | | | | | |
| 2 | VSS | Signal GND | | | | | | |
| 3 | Сх | Sense electrode | Connect to conductive area intended for sensor | | | | | |
| 4 | VDDHI | Supply Input | Supply:1.8V – 3.3V | | | | | |
| 5 | VREG | Regulator output | Requires external capacitor | | | | | |
| 6 | NC | | | | | | | |
| 7 | NC | | | | | | | |
| 8 | SECONDARY I/O | Digital Input/Output | Multifunction IO2 / SDA (I ² C Data output) | | | | | |
| 9 | PRIMARY I/O | Digital Input/Output | Multifunction IO1 / SCL (I ² C Clock signal) | | | | | |
| 10 | NC | | | | | | | |

Table 1.3 Multifunction pin descriptions

| Multifunction pin name | Multifunction pin option |
|------------------------|--|
| IO1 | Proximity output / Proximity output with heartbeat |
| IO2 | Sensitivity input / Synchronization input / |
| | Movement output / Touch output |





2 Summary: Package and pin-out (WLCSP)

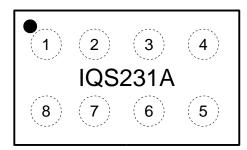


Figure 2.1 IQS231A 8-pin WLCSP (top view)

Table 2.2 8-pin WLCSP Pin-out description

| | IQS231A 8-pin WLCSP | | | | | | |
|-----|---------------------|----------------------|---|--|--|--|--|
| Pin | Name | Туре | Function | | | | |
| 1 | Сх | Sense electrode | Connect to conductive area intended for sensor | | | | |
| 2 | PRIMARY I/O | Digital Input/Output | Multifunction IO1 / SCL (I ² C Clock signal) | | | | |
| 3 | VREG | Regulator output | Requires external capacitor | | | | |
| 4 | VSS | Signal GND | | | | | |
| 5 | NC | Digital Input/Output | Not used. Floating input during runtime. Recommended: Connect to GND | | | | |
| 6 | SECONDARY I/O | Digital Input/Output | Multifunction IO2 / SDA (I ² C Data output) | | | | |
| 7 | VDDHI | Supply Input | Supply:1.8V – 3.3V | | | | |
| 8 | PGM | Configuration pin | Connection for OTP programming. Floating input during runtime. Recommended: Leave NC for programmed ICs. Connect separate pad/pin for in-circuit programming (separate modules only) | | | | |





3 Reference Schematics:

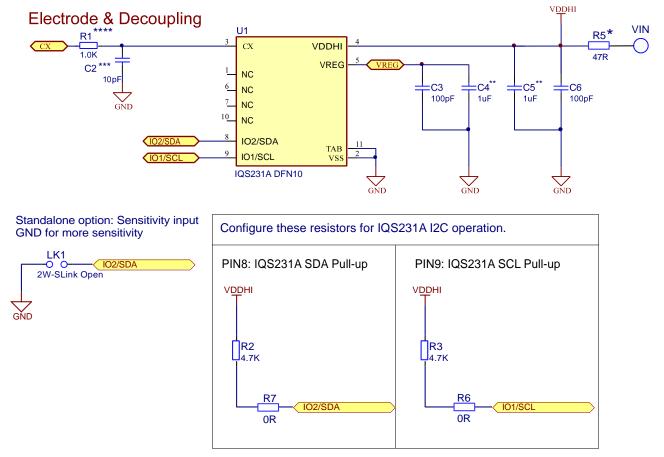


Figure 3.1 IQS231A DFN10 reference schematic

Footnotes:

- * R5: Place a 47 Ω resistor in the VDDHI supply line to prevent a potential ESD induced latch-up. Maximum supply current should be limited to 80mA on the IQS231A VDDHI pin to prevent latch-up.
- ** C4 & C5: Choose these capacitors based on the selected sampling rate. The target is to prevent the VREG voltage to drop more than 50mV from its regulated value during a sleep cycle (see Figure 10.1).

| | 30Hz | 100Hz | 8Hz | 4Hz |
|----|------|-------|-------|-------|
| C4 | 1uF | 1uF | 2.2uF | 4.7uF |
| C5 | 1uF | 1uF | 4.7uF | 10uF |

- ***C2: Example load of 10pF. This value may vary to adjust sensitivity. 1pF for higher sensitivity and up to 60pF for proximity detection use. A total load capacitance of 200pF is allowed by the sensing system.
- ****R1: Vary this value to control the RC slope of the capacitance measurement signal. Use for harmonic suppression and to enable a high impedance sensing path in a low impedance system.





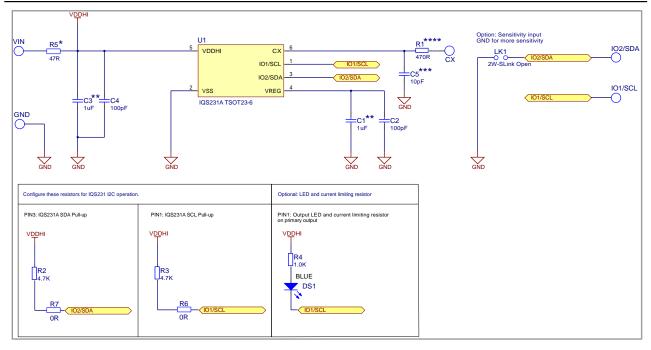


Figure 3.2 IQS231A TSOT23-6 reference schematic

Footnotes:

- * R5: Place a 47Ω resistor in the VDDHI supply line to prevent a potential ESD induced latch-up. Maximum supply current should be limited to 80mA on the IQS231A VDDHI pin to prevent latch-up.
- ** C1 & C3: Choose these capacitors based on the selected sampling rate. The target is to prevent the VREG voltage to drop more than 50mV from its regulated value during a sleep cycle (see Figure 10.1).

| | 30Hz | 100Hz | 8Hz | 4Hz |
|----|------|-------|-------|-------|
| C1 | 1uF | 1uF | 2.2uF | 4.7uF |
| C3 | 1uF | 1uF | 4.7uF | 10uF |

- ***C5: Example load of 10pF. This value may vary to adjust sensitivity. 1pF for higher sensitivity and up to 60pF for proximity detection use. A total load of 200pF is allowed by the sensing system.
- ****R1: Vary this value to control the RC slope of the capacitance measurement signal. Use for harmonic suppression and to enable a high impedance sensing path in a low impedance system.





4 Summary: One-Time-Programmable (OTP) options

| OTP bank 0 IQS231A 000000 <u>xx</u> TSR | | | | | | | |
|---|---|---|---|---|---|---|--|
| Bit7 | 6 | 5 | 4 | 3 | 2 | 1 Bit 0 | |
| Movement ti | me-out | Reserved | Reserved Movement Quick release threshold | | | Quick release beta | |
| Prox no mov UI 00 - 2s 01 - 5s 10 - 10s 11 - Disabled (Prox&Mov Uis 00 - 10s 01 - 30s 10 - 60s 11 - 10min | n/a 0 - 4 counts 00 - n 1 - 6 counts 01 - s 10 - r 11 - v | | 00 - moderate 100 counts 00 - 2 (fast following) 01 - strict 150 01 - 3 10 - relaxed 50 10 - 4 11 - very strict 250 11 - 5 (slow following) | | | | |
| | accuracy section | 10 | 00044 000 | 000 TOD | | | |
| OTP Bank | | | S231A 000 | | | | |
| Bit7 I2C address | | Proximity Thres (low/high) | l 4 shold | AC Filter | 2 | Touch threshold | |
| 00 – standalone 01 – 44H 10 – 46H 11 – 47H | | Sensitivity input low / Sync input active / Mov output / Touch output 00 – 4 counts (¹Warning) 01 – 6 10 – 8 11 – 10 Sensitivity input high (internal 20kΩ pull-up) 00 – 8 counts 01 – 10 10 – 12 11 – 14 | | 00 - 1 01 - 2 10 - 3 11 - 0 | | 00 – 32 counts 01 – 64 10 – 256 11 – 320 | |
| OTP Bank | | | S231A 00 <u>x</u> | | | | |
| Bit7 | 6 | 5 | 4 | 3 | 2 | 1 Bit 0 | |
| Increase debounce | Target | Base value | | Failsafe | Quick release | User interface | |
| 0 – 6in, 4out 1 – 12in, 8out | 0 = 1200 / 1096 (movement) 1 = 768 | 00 – 100 counts 01 – 75 10 – 150 11 – 200 | | 0 – Disabled 1 – Enabled 1 – Disabled | | 00 – Prox / No movement 01 – Prox with movement 10 – Prox with movement / Touch with no movement 11 – Same as '10', touch output forced on IO2 | |
| OTP Bank 3 IQS231A <u>xx</u> 0000000 TSR | | | | | | | |
| Bit7 | Bit7 6 | | 4 | 3 | 2 | 1 Bit 0 | |
| Charge transfrequency | e transfer Temperature IO2 function | | | | Sample rate | | |
| 00 – 500kHz 01 – 125 kHz 10 – 64 kHz 11 – 16.5kHz | 00 – 500kHz 0 – Disabled 00 – Sensitivity 01 – 125 kHz 1 – Enabled (proximity thres 10 – 64 kHz 01 – Sync input | | hold adjust) t t output | 0 – Enabled 1 – Disabled | Sample-to-sample time (Response time) Includes 6 sample debounce burst of 24ms 00 – 30 Hz (57ms) 01 – 100 Hz (34ms) 10 – 8 Hz (154ms) 11 – 4 Hz (280ms) *See time-out accuracy section 9.8 & 9.9 | | |

¹Careful design is key when using a threshold of 4 combined with a base value of 100 / 75 and a target of 1200. Contact Azoteq.





5 Summary: Programming reference (I²C memory map)

| 6.4.2 | Donata . | - h | l 5 | | | inications Layout | T | | | | |
|------------------------------|--------------------------------------|--------|------------------|---|---|---|---|--|--|------------------------|------------------|
| Address/ Command/ Byte | Register name/s | R/W | Default Value | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit (|
| DEFAULT COMMS | MAIN_EVENTS | R | n/a | | DEBUG | SENSING DISABLED | WARM BOOT | COLD BOOT | RELEASE | TOUCH | PROX |
| POINTER | | Fach r | ead instruct | ion returns 'MA | IN FVFNTS' hvte : | as first byte, follow | ed by the data a | at the specified a | ddress | | |
| 00H | PRODUCT NUMBER | R | 0x40 | ion returns win | IIV_EVENTS Byte t | as mist byte, ronow | | (40 | 341633 | | |
| 01H | SOFTWARE VERSION | R | 0x06 | | | | | «06 | | | |
| 02H | DEBUG_EVENTS | R | n/a | RESERVED | ATI_ERROR | CH0_ATI | RESERVED | QUICK RELEASE | EXIT MOV DETECT | ENTER MOV DETECT | MOVEMENT |
| 03H | Reserved | R/W | n/a | | | | | RVED | | | |
| 04H | COMMANDS | R/W | 0x00 | ATI_CH0 | DISABLE SENSING | ENABLE SENSING | TOGGLE AC FILTER | RESERVED | TOGGLE ULP MODE | RESERVED | WARM BOOT |
| 05H | OTP Bank 1 | R/W | 0x00 | Standalone / | | Proximity thres | | AC Filter | WIODE | Touch thresh | |
| | | | | | | Read only | | | 1 | Read only | |
| 06H | OTP Bank 2 | R/W | 0x00 | Increase debounce | Target | Base value | | Failsafe pulses IO1 | Quick release | User interfac | e selection |
| 07H | OTP Bank 3 | R/W | 0x00 | Charge transf | er frequency | Temperature & interference compensation | IO2 Function | | ATI events on IO1 | Sample rate | |
| 08H | QUICK RELEASE | R/W | 0x00 | | Quick release | threshold LUT | II. | | Quick relea | se beta | |
| | | | | 0xC = 500 0xD = 750 | 0x8 = 75 0x9 = 200 | 0x4 = 10 0x5 = 20 | 0x0 = 100 0x1 = 150 | | | | |
| | | | | 0xE = 850 | 0xA = 300 | 0x6 = 25 | 0x2 = 50 | | | | |
| 09H | MOVEMENT | R/W | 0x34 | 0xF = 1000 | 0xB = 400 Filter b | 0x7 = 30 nalt time | 0x3 = 250 | | | | |
| ОЭП | MOVEMENT | K/ W | (2s, 8) | 0xC = 10min | 0x8 = 30s | 0x4 = 4s | 0x0 = 0s | | Movement thresho | old = (Value × 2) | |
| | | | (-, -, | 0xD = 30min 0xE = 60min | 0x9 = 1min | 0x5 = 5s | 0x1 = 0.5s 0x2 = 1s | | Available ran | | |
| | | | | 0xF = 90min | 0xA = 2min 0xB = 5min | 0x6 = 10s 0x7 = 20s | 0x2 = 1s 0x3 = 2s | | 0 = always move | ment trigger | |
| 0AH | TOUCH THRESHOLD | R/W | 0x07 | | | | | I = (Value × 4) + 4 | | | |
| OBH | PROXIMITY | R/W | (32) 0x00 | | Pace | erved | Available ra | nge: 4 – 1024 Reserved | | 00 – 4 count | e e |
| ОВП | THRESHOLD | N/ VV | 0,000 | | Kesi | erveu | | Reserved | | 01 – 6 | • |
| | | | | | | | | | | 10 – 8 | |
| 0011 | | 2011 | 0.00 | | | | | | | 11 – 10 | |
| 0CH | Temperature & interference threshold | R/W | 0x03 | | Temperature tracking threshold when not in touch / prox detect | | | | | | |
| 0DH | CH0 Multipliers | R/W | n/a | Reserved | Reserved | CH0 Sensitivit | | | CH0 Compensati | | |
| 0EH | CHO Componentian | R/W | 2/2 | | | 0- | | 255 | 0-1 | 5 | |
| 0FH | CH0 Compensation CH1 Multipliers | R/W | n/a n/a | Reserved | Reserved | CH1 Sensitivit | | 255 | CH1 Compensati | on multiplier | |
| 0111 | CITE Widelphicis | 10,00 | 11/4 | Neserveu | Reserved | 0- | | | 0-1 | | |
| 10H | CH1 Compensation | R/W | n/a | | | | 0 - | 255 | | | |
| 11H | System flags | R | n/a | I2C | TEMP | CH1_ACTIVE | CURRENT_CH | NO SYNC | CH0_LTA_HALTED | ATI_MODE | ZOOM MODE |
| 12H | UI flags | R | n/a | TEMP CHANNEL ATI | TEMPERATURE RESEED | Reserved | UI AUTO ATI OFF | UI SENSING DISABLED | QUICK_RELEASE | Reserved | OUTPUT ACTIVE |
| 13H | ATI flags | R | n/a | CHARLETTI | NEGLEG | I | | erved | I. | l | 7101172 |
| 14H | Event flags | R | n/a | CH1_ATI | Reserved | | CH1 | CH0_ATI | CH0 | CH0_ | CH0_PROX |
| 15H | CH0 ACF H | R | n/a | ERROR | | Pro | MOVEMENT | ERROR Filtered count va | UNDEBOUNCED | TOUCH | |
| 16H | CHO ACF L | R | n/a | | | 110 | | 2000 | iide | | |
| 17H | CHO LTA H | R | n/a | | | Proximity char | inel: Reference o | count value (Long | term average) | | |
| 18H | CHO LTA L | R | n/a | | | • | | 2000 | | | |
| 19H | CH0 QRD_H | R | n/a | | | Proximity c | hannel: Quick re | lease detect refe | rence value | | |
| 1AH | CH0 QRD_L | R | n/a | Proximity channel: Quick release detect reference value 0 – 2000 | | | | | | | |
| 1BH | CH1 ACF_H | R | n/a | | | Mo | | : Filtered count v | alue | | |
| 1CH | CH1 ACF_L | R | n/a | | | | | 2000 | | | |
| 1DH | CH1 UMOV_H | R | n/a | | | Movem | | per reference cou | int value | | |
| 1EH | CH1 UMOV_L | R | n/a | 0-2000 | | | | | | | |
| 1FH 20H | CH1 LMOV_H CH1 LMOV L | R R | n/a n/a | Movement channel: Lower reference count value 0 − 2000 | | | | | | | |
| 21H | CH1 RAW H | R | n/a | | Tem | nerature channel: | | | ature feature enabl | ed) | |
| 22H | CH1_RAW_L | R | n/a | | Telli | perature chamiles. | | 2000 | acare reacure enabl | | |
| 23H | TEMPERATURE_H | R | n/a | | Movem | ent channel tempe | rature reference | e (a previous valu | e of temperature ch | nannel) | |
| 24H | TEMPERATURE_L | R | n/a | | | <u> </u> | 0 – | 2000 | | | |
| 25H | LTA_HALT_TIMER_H | R | n/a | | Countdown ti | | | | ment events will res | et this timer | |
| 2011 | LTA_HALT_TIMER_L | R | n/a | | (0 – 255) × 100ms Timer range: 0 – 90min | | | | | | |
| 26H | | | | | Countdown timer to give active feedback on the fixed 5sec time-out when in filter halt mode (before entering Proximity detect) 0 – 50 x 100ms Timer range: 0 – 5 seconds | | | | | | |
| 27H | FILTER_HALT_TIMER | R | n/a | Countdown ti | mer to give active | 0 – 50 | 0 x 100ms Time | er range: 0 – 5 se | conds | entering Proxim | ity detect) |
| | FILTER_HALT_TIMER TIMER_READ_INPUT | R R | n/a n/a | Countdown ti | mer to give active | 0 – 50 Countdown time | 0 x 100ms Time er to signal whe | er range: 0 – 5 se n a read operatio | n is done on IO2 | entering Proxim | ity detect) |
| 27H | | | | Countdown ti | <u>-</u> | 0 – 50 Countdown time (0 – 10 er to give active fe | 0 x 100ms Time er to signal when 0) x 100ms Time edback on the t | er range: 0 – 5 se n a read operatio ier range: 0 – 1 se | conds n is done on IO2 econds ration is attempted | | |





6 Functional block diagram

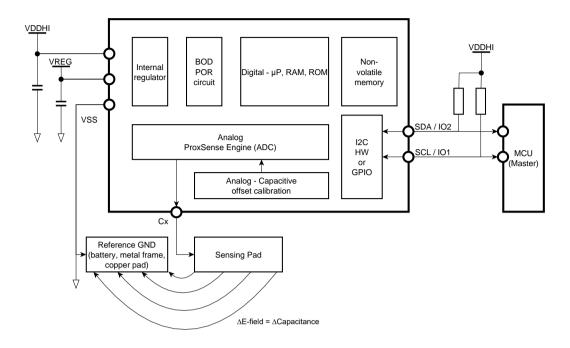


Figure 6.1 IQS231A functional block diagram

The IQS231A supports relative capacitance measurements for detecting capacitance changes. Basic features of the IQS231A include:

- Charge-transfer capacitance measurement technology (Analog ProxSense Engine)
- Finite state machine to automate detection and environmental compensation without MCU interaction (integrated microprocessor)
- Self-capacitance measurements
- Configuration allows sequential capacitance measurements (one sensing pin with two time-slots)
- Signal conditioning to provide signal gain (Analog Capacitive offset calibration)
- Signal conditioning to provide offset compensation for parasitic capacitance (Analog Capacitive offset calibration)
- Integrated calibration capacitors (Analog Capacitive offset calibration)
- Integrated timer for timer triggered conversions
- Integrated LDO regulator for increased immunity to power supply noise
- Integrated oscillator
- Processing logic to perform measurement filtering, environmental compensation, threshold detection and movement detection





7 Summary: Features

| Pin compatibility | Designs using the IQS229 or IQS128 will benefit from a "drop-in" replacement on a production device for evaluation. Using the added I ² C capability on the IQS231A will require an added connection to the master device. | | | | |
|--|---|--|--|--|--|
| | A DYCAL-type implementation (referring to dynamic threshold calibration) is recommended as main stability feature for the latest SAR user interface. Passing the device SAR qualification with this type of interface has been proven successful. | | | | |
| | "Quick release" detection is the improved "DYCAL"-type implementation and focusses on a release characteristic within a time window. | | | | |
| Y | Movement features add a second level of protection against stuck conditions with the quick release detection. | | | | |
| DYCAL / Quick release | The quick release will be detected on the proximity channel (not the secondary movement channel) and the signal slope will be monitored to enable the quick release. A single action from a touch/proximity state will trigger the quick release event and the event will only remain as long the proximity state holds. | | | | |
| | A number of features are offered to ensure operation in various designs where high power RF signals may influence the sensing signal: | | | | |
| Control in RF environments | Increased low frequency sensing options to allow for high impedance filter circuits Increased debounce option to prevent RF noise triggers Advanced temperature compensation for fast temperature variations caused by high power RF circuits Interference compensation for false triggers caused by conducted/radiated noise. | | | | |
| Advanced temperature & interference compensation | An improved compensation feature is offered to prevent false triggers due to quickly varying temperature & high interference environments. This feature effectively tracks temperature changes & compensates for interference only when no proximity trigger is present. | | | | |
| | The device offers 3 main Uis intended for SAR use. These are: | | | | |
| UI | Proximity UI, no continuous movement sensing Proximity UI, continuous movement sensing Proximity & touch UI, continuous movement sensing during proximity, no movement sensing during touch (No time-out during long duration stationary SAR tests) | | | | |
| User interface selection | In all cases the use of the quick release feature is recommended to prevent typical non-human activations from remaining. | | | | |
| | In all cases "no movement" and "movement sensing" refers to the capacitive movement sensing during normal activation. "Hand held detection" and "quick release" features will enable | | | | |





movement sensing with a no-movement time-out, irrespective of which UI is selected.

Summary: Features (Continued 1...)

| | , |
|---------------------------------------|---|
| | Movement detection is designed to function as human presence detection in a localized area. This device can't be used to fulfil an accelerometer function ("G-sensor" function). |
| Movement detection | Human presence detection requires an exception in SAR testing because the qualification testing only uses stationary "phantom bodies". Optimized human detection is offered through an integrated separate channel, dedicated towards human detection. |
| | Default input use: internal pull-up ($20k\Omega$) by default, tie directly to GND for more sensitive option. |
| Sensitivity adjustment | Apart from the simple external adjustment, an external capacitor is recommended for sensitivity adjustments. 1pF is considered a small change in sensitivity, while 10pF changes are considered large. A maximum of 60pF load is recommended for effective proximity sensing. |
| Cx | A single pulse of 500µs is integrated on IO1. This pulse is the failsafe heartbeat, sent on each sensing event. This pulse will be sent during the "stabilize time" as shown in Figure 10.1. |
| IO1 Fails afo hoarthoat | The failsafe indicator signal will precede the conversions (sampling). The failsafe signal will be repeated during burst mode in order to offer synchronization output to the master, indicating exactly when sensitive measurements are done. Measurement times have a fixed maximum which the user can implement. |
| Failsafe heartbeat | The failsafe signal is disabled by default and may be enabled via OTP option or I ² C initialize with standalone setup. |
| High configurability | Through I ² C the IQS231A can be used in many different ways and the configuration can be updated during later stages of development than with the OTP route. |
| Switch I ² C to standalone | Configure the device via a dedicated I ² C type connection and switch to any standalone mode for runtime operation. This minimises the processor load and spurious content from communication signals. |
| | Unexpected reset conditions should be managed via the failsafe pulse OTP option or by polling the device periodically. When the heartbeat disappears or I2C responds to the polling, default state applies and the master should reconfigure the device through I ² C. |





Summary: Features (Continued 2...)

| Sync input | In order to ensure a stable sensing environment, sensing may be done in strategic time windows controlled by a master device. | | |
|-------------------------------------|--|--|--|
| | The Automatic tuning implementation (ATI) ensures optimal sensitivity during runtime for various sensor environments. | | |
| Automatic tuning (ATI) | Two channels are calibrated (proximity channel and movement channel). Both run on the same Cx pin in different time slots. | | |
| (ATI) | An ATI-block time is defined to prevent re-ATI loops during touch release events. The ATI-block is fixed for the movement channel, and fixed for the standard touch/proximity channel | | |
| Reference signal behaviour | Long-term-average (LTA: signal reference) behavior is optimized for SAR where trigger tests are important in product qualification. The LTA will therefore be slow while still able to prevent typical temperature drift from causing activations. | | |
| Start Control Byte | Standard I ² C polling for: | | |
| S Adr + WRITE ACK | Debugging & normal use | | |
| Improved I ² C interface | Device polling optimized for guaranteed response (within t_{CLK_stretch} – clock stretching will be applied to the bus SCL line) | | |





8 Features: Extended details

8.1 ATI (Automatic Tuning Implementation)

External sensor connections are calibrated in the following ways:

- Power On Reset (proximity channel is calibrated at each POR)
- Movement channel is only calibrated with POR when hand-held detection is enabled
- Proximity & movement channel is calibrated when the reference is out of bounds (1/8 of target counts). The reference of the proximity channel is rapidly adapted when capacitance moves away from the trigger threshold OR when an automatic "reseed" is done (Reseed: reference = actual sensor value). The reference of the movement channel is rapidly adapted in any direction of capacitive changes.
- Redo-ATI of the proximity channel can be initiated by the user in I²C mode using an I²C command.

During each proximity channel ATI event, the proximity output is activated to indicate the event and ensure a safe output during the event and in the case of an ATI-error.

8.2 Sensitivity adjustment

Apart from the simple external adjustment, an external capacitor is recommended for sensitivity adjustments. 1pF is considered a small change in sensitivity, while 10pF changes are considered large. A maximum of 60pF load is recommended for effective proximity sensing.





9 I²C Programming Guide (Summary)

The IQS231A device interfaces to a master controller via a 2-wire (SDA and SCL) serial interface bus that is I^2C^{TM} compatible, with a maximum communication speed of 400kbit/s.

The protocol acknowledges an address request independently. The I²C hardware module is awake for address recognition while the IQS231A is in sleep mode, giving the ability to wake the device at any time and effectively communicate via serial interface. This is different compared to other ultra-low power Azoteq solutions where the communications module also sleeps during standard IC sleep times. Repeated polling requests where required in such case.

9.1 Add I2C connection

When using I²C mode, ensure the connections as shown in Figure 1.. Internal pull-up resistors are sufficient for communication speeds up to 100kbits/s with low capacitance on the lines (<15pF). For 400kbit/s, be sure to place pull-up resistors (4.7k Ω recommended)

9.2 I2C command structure

By writing to address 0x04, commands are sent to the device. The commands are as follows:

Table 9.1 I²C command structure

| Reg 0x04 Bit | Name | Description | Toggle (yes/no) |
|--------------|-----------------|------------------------|-----------------|
| 0 | SWITCH TO | Switch from I2C so | No |
| | STANDALONE | standalone outputs | |
| | (warm boot) | Soft reset, all | |
| | | registers remain as | |
| | | written, UI resets | |
| 1 | AUTO ATI | Enable or disable | Yes |
| | | automatic calibration | |
| | | when sensing signal | |
| | | is out of bounds | |
| 2-4 | RESERVED | n/a | n/a |
| | | | |
| 5 | | Disables all | Ne |
| 5 | DISABLE SENSING | Disables all | No |
| | | conversions | |
| 6 | ENABLE SENSING | Enable capacitive | No |
| | | sensing | |
| 7 | ATI CH0 | Perform re-calibration | No |
| | | on proximity channel | |





9.3 Control Byte

The Control byte indicates the 7-bit device address (44H default) and the Read/Write indicator bit. The structure of the control byte is shown in Figure 9.1.

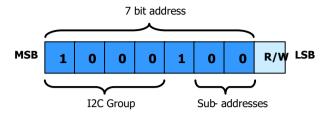


Figure 9.1 IQS231A control byte

The I²C device has a 7 bit Slave Address (default 0x44H) in the control byte as shown in Figure 9.1. To confirm the address, the software compares the received address with the device address. Sub-address values can be set by OTP programming options.

The IQS231A has alternate slave address options of 0x46 and 0x47.

9.4 Test mode (address 0x45)

During the power-on period (t_{test_mode}) the device will respond to polling requests on address **0x45** (test-mode address). Test-mode is used during IC production and OTP (programming) configuration.

With another device on the I²C bus with address 0x45, power-up sequence and communication timing should be considered.

9.5 I2C typical setup

The typical I²C setup would adjust the following registers:

- Quick release beta
- Quick release threshold
- Movement threshold
- Touch threshold
- · Proximity threshold
- Filter halt time
- User interface
- IC mode

The rest of the settings will only require adjustment with specific requirement.

9.6 I2C read (Event register)

Each I2C read will always return the event register (default address pointer) as the first byte. When reading from a specific register (write address before read), 2x reads should be done. See memory map first line for detail on the event register.

When reading without writing an address, the main events register data (default address pointer) is returned. Consecutive reads will step through the memory map, starting from address 0x00 after the default address pointer.





9.7 I2C polling and sensing timing

Polling may be done at any time. Polling of the specific device will dictate the sensing rate.

Series resistance (example schematic R6 = R_{I2C_series} & R7 = R_{I2C_series}) on the I^2C lines are effective in preventing interference on sensitive configurations. R_{I2C_series} is recommended for using the IQS231A on a bus with other devices.

9.8 Movement time-out accuracy

When I²C mode is enabled (OTP bank 1 bit7:6 is not "00") the time out settings in register 0x09 bit7:4 will respond as shown in the graph below (typical measured values for a constant polling rate):

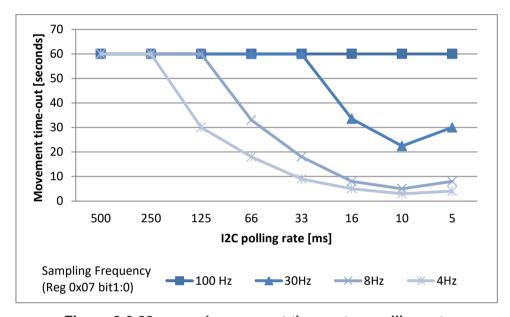


Figure 9.2 60 second movement time-out vs polling rate

While any polling rate is acceptable for 100Hz sampling, it is recommended to poll slower than the sampling frequency in order to keep an accurate time-out.

9.9 Sampling frequency vs sensing frequency

Sampling frequency (Reg 0x07 bit1:0) is the rate at which samples are taken by the sensor. The sensing frequency (Reg 0x07 bit7:6), or "charge transfer frequency" is the frequency at which the complete capacitive load is charged and discharged.

Depending on the charge transfer frequency, the sampling frequency is automatically adapted to accurately complete charge transfers for 30Hz (default) mode. For 100Hz mode, performance is prioritized and sampling time may vary during "Prox with movement" UIs or "Temperature & interference compensation" enabled. In such case, Reg 0x07 bit1:0 is not forced to a different value. The automatic adapt is done as shown in Figure 9.3



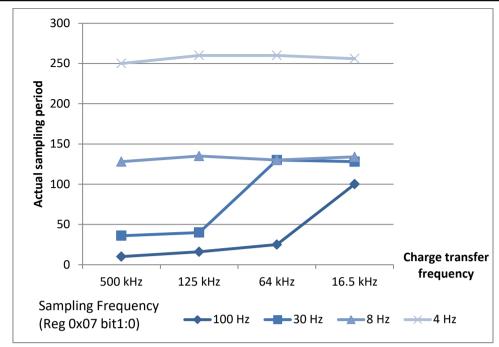


Figure 9.3 Actual sampling period vs sampling frequency selected¹

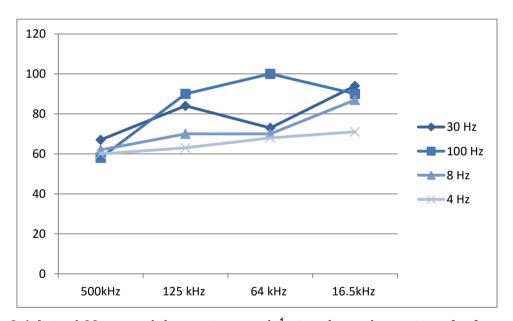


Figure 9.4 Actual 60 second time-out example 1 at various charge transfer frequencies

¹Testing was done to obtain typical values using the recommended schematic as in Figure 3.2 (1uF capacitors for C1 & C3) at 25°C.





10 Configuration Options

The IQS231A offers various user selectable options. These options may be defined via I²C setup or **one-time programmable (OTP)** configuration. OTP configured devices may be ordered pre-programmed for bulk orders or in-circuit programming techniques may be implemented during the product testing phase. I²C setup allows access to all device settings while entering direct output mode when selected by the MCU.

Azoteq offers a Configuration Tool (CT210 or later) and associated software that can be used to program the OTP user options for prototyping purposes. For further information regarding this subject, please contact your local distributor or submit enquiries to Azoteq at: ProxSenseSupport@azoteq.com

10.1 OTP Details: Bank 0

| Movement time- out (bit 7:6) | When no movement is detected within a time period, a movement time-out occurs. The reference is halted until the timer clears. After the timer clears, the reference signal is made equal to the actual signal, nullifying any signal delta that may have caused a proximity or touch event. The timer is reloaded with every movement event detected. | | |
|---|---|--|--|
| Movement threshold (bit 4) | A low count threshold region is defined for a movement signal internally stored. Movement characteristics accumulate and triggers as soon as it reaches the threshold. The accumulated effect restarts in order to detect the next possible movement event. | | |
| Quick release threshold (bit 3:2) | The quick release feature will operate according to the parameters as specified in: • DYCAL / Quick release definition • Quick release beta • Quick release threshold The quick release threshold defines the trigger point for the feature where the counts deviate from a quick release moving average in a certain direction. The direction is with increasing counts | | |
| Quick release beta (bit 1:0) | The quick release beta forms part of the quick release feature and is the filter intensity of the reference value used to follow the actual counts. The quick release triggers according to the difference between this reference value and the actual counts. When this value is large, the quick release will trigger for a variety of release types from slow to fast releases. When this value is small, the quick release will only trigger for fast releases. | | |





10.2 OTP Details: Bank 1

| | , |
|---------------------------------|---|
| IC mode | Standalone (default), or I2C. |
| (bit 7:6) | Use I ² C for runtime operation, or switch to standalone after initializing the device |
| | The advantage of this "runtime" option is explained in the Switch I ² C to standalone section of the features summary. |
| | When choosing I2C, the address options of $0x44$, $0x46$ and $0x47$ exist. Avoid the use of address $0x45$ on this I ² C-bus, this could activate a test mode in the IC during a power-up window. |
| Proximity Threshold | By default this is the only trigger threshold in the system (touch threshold also available). |
| (low/high) (bit 5:4) | The threshold is adjustable in actual counts values (count values can be seen when streaming I2C value through the IQS231A GUI). The threshold is the amount of counts the actual signal falls below the reference signal (long-term average) |
| | In the default configuration the input pin IO2 will be active. IO2 = VSS will enable the chosen option in the OTP (4-10 counts) IO2 = VDDHI (8-14 counts) |
| | The system will default to the IO2 = VSS option when sync input or movement output is enabled. |
| AC Filter (bit 3:2) | Incoming samples are slightly filtered by default (AC filter = 1). This option gives the ability to significantly increase the filter strength. Default is an IIR (infinite impulse response) filter of 2 (2^1). The "increased" options enables an IIR filter of 4 (2^2) or 8 (2^3). |
| | Movement detection is not affected by this setting. For movement detection the IIR filter is fixed on AC filter = 2. |
| Touch threshold (bit 1:0) | Threshold in counts that defines the level below the proximity threshold that cancels a quick release event and disables any active movement detection. |
| • | |

10.3 OTP Details: Bank 2

| Increase Debounce (bit 7) | Once a threshold is crossed, a rapid debounce action ensures performance in low SNR environments and short reaction time in low power modes. An increased debounce is offered for situations where RF noise coupling into the sensor is large |
|---------------------------------|---|
| Target (bit 6) | The target count is an offset value of the actual system capacitance. The actual signal (expressed in counts) will be calibrated as close as possible to this value. |
| | A larger target optimizes sensitivity at the cost of charge transfer time. A lower target offers more stability, but less sensitivity. |
| Base value | The base value is a lower target value for the actual signal and implies the system gain. A base value of 100 and target of 1000 implies a x10 |





| (bit 5:4) | gain, while base value of 200 and target of 1000 implies a x5 gain. | | | | | |
|-----------|--|--|--|--|--|--|
| Failsafe | This bit is only has an effect when User interface is set to Standalone. | | | | | |
| (bit 3) | The output IO1 will have pulses superimposed on the regular output (pulse duration t_{failsafe}), separated by the sampling period. A pulse will be on output every time a capacitive conversion is done. Conversion rate and debounce events may be debugged through this output. | | | | | |
| | Scan time Crx1 (touch Crx1 & prox) (movement) Stabilize time Response (standalone) | | | | | |
| | Figure 10.1 Conversion signal on Cx timing description | | | | | |
| | Normal conversion rate Burst mode to debounce proximity event | | | | | |
| | Cx | | | | | |
| | IO1 No prox Prox detected | | | | | |
| | Figure 10.2 Conversion diagram with failsafe output signal | | | | | |





OTP Details: Bank 2 (...continued)

Quick release

The guick release feature can be disabled here (enabled by default).

The quick release feature offers improved user experience and does not influence trigger performance. The feature is directed at SAR applications, but also has significant benefits for long-term detection applications.

The touch depth and speed of release is used to detect the instance where the user interaction implies a release condition. This is required for cases where the normal threshold release is not triggered for any of the following reasons:

- Device placed on table while releasing the hand (the capacitive influence of the table remains)
- Place device inside a bag while releasing the hand (the capacitive influence of the bag remains)
- Fit a protective cover during use (the capacitive influence of the cover remains)
- Extreme temperature (cool down) shift causes a shift in capacitive environment
- Capacitance impulse recovery (drop test, transient bursts etc)

User interface (bit 1:0)

When movement Uis are enabled, the timeout is only active in the proximity region. When in touch, only quick release can get the IC out of a stuck condition. In such case no movement time-out for quick release is fixed at 2sec and no-movement time-out for proximity is as defined in OTPs

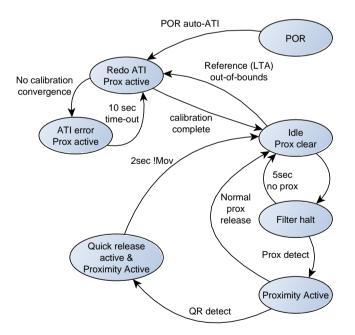


Figure 10.3 Proximity UI no movement





OTP Details: Bank 2 (...continued)

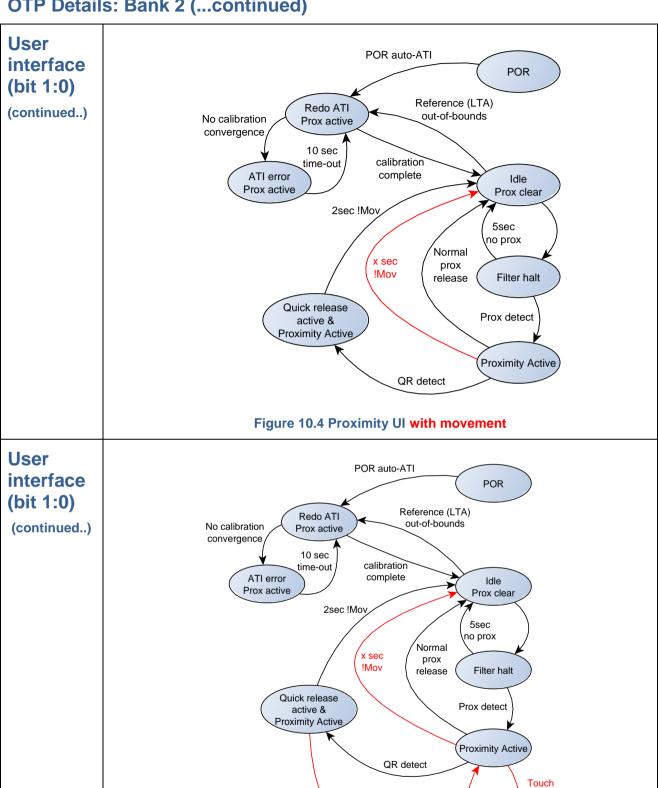


Figure 10.5 Proximity & touch UI (with movement enabled in proximity & movement disabled in touch)

Touch detect

QR cancelled

Normal

touch

release

Touch Active

detect





10.4 OTP Details: Bank 3

| 10.40 IP Details: Bank 3 | | | | | |
|---|--|--|--|--|--|
| Charge Transfer frequency (bit 7:6) | Various charge transfer frequencies are offered to allow for standard reference design filters to highly resistive and reactive filter elements. These options give the ability to retain signal integrity along with the isolation properties of the filter elements. These options are useful for hybrid antenna designs where the RF and sensing signal share the same conductive structure. | | | | |
| Temperature & Interference Compensation (bit 5) | Advanced temperature compensation is disabled by default. When enabled the IQS231A is able to track strong temperature changes when a proximity is not detected. This may be required when the sensor is placed on a PCB with highly varying temperature effects (example: close to an RF amplifier) | | | | |
| IO2 function (bit 4:3) | By default IO2 will be a sensitivity adjustment input. An internal pull-up (R _{internal}) will by default select a less sensitive option (IO2 = VDDHI). By strapping then pin directly to Vss, a more sensitive option is selected (IO2 = VSS). When the movement output is enabled, the input defaults to the "more sensitive option" as shown with IO2 = VSS With the output enabled the movement events are shown on IO2. The output is in an active low, open drain configuration. The output will remain low for tawake when movement is detected and this will occur during the sample time after the movement trigger occurs (the movement trigger is delayed with the sample rate) Sync input: The input (pin IO2) may be used to detect when to sense and when to halt the sensing. MCU GPIO SYNC PULSE SYNC PULSE SYNC PULSE SYNC PULSE SYNC PULSE Figure 10.6 Sync input of the IQS231A | | | | |
| ATI events on IO1 (bit 2) | Calibration events (ATI) are shown on the standalone output pin (IO1). During this time, the calibration is active and proximity events during this time may influence the calibration time. The output is enabled by default and can be disabled through this bit | | | | |
| Sample rate (bit 1:0) | The various sample rates offered are mainly given for the user to determine an ideal balance between power consumption and response time. Overall response times of the IQS231A are improved with SAR trigger testing in mind. It is recommended to reduce or disable AC-filtering when using lower power modes to improve reaction time. | | | | |

power modes to improve reaction time.





11 Full programming reference

A detailed list of the I^2C registers follows and follows the structure of the memory map summary on page 9.

| Summa | ary on page 9. | | |
|-------|------------------|-----|---|
| ADDR | | Bit | Description |
| xxH | MAIN_EVENTS | 7 | n/a |
| | | 6 | OFNIGING DIGABLED. As indicating of face of a simplified times |
| | | 5 | SENSING DISABLED – An indication of forced or implied times when no sensing signals are applied to the sense pin. When this |
| | | | bit is set and bit 2 is cleared, sensing is disabled. When this bit |
| | | | and bit 2 is set, sensing is enabled again. |
| | | 4 | WARM BOOT – A software reset command in register 0x04 will |
| | | | lead to a warm boot. This will imply a reset for the user interface |
| | | | and re-calibration will be triggered. |
| | | 3 | COLD BOOT – A hard reset (power supply cycle) will cause all |
| | | | registers to return to a default value. This indicator will imply the |
| | | _ | need to re-initialize the device. |
| | | 2 | RELEASE – A touch, prox or sensing event may be paired with a release indication to show an exit of the flagged event. |
| | | 1 | TOUCH – Disabled by default, this bit will be active when a |
| | | ' | touch and prox user interface is chosen. |
| | | 0 | PROX - The main feedback bit to indicate an activation |
| 00H | PRODUCT_ | n/a | The product number is fixed at 0x40 |
| | NUMBER | | |
| 01H | SOFTWARE_ | n/a | The software version is 0x06 for IQS231A |
| 0211 | VERSION | 7 | n/a |
| 02H | DEBUG_ EVENTS | 6 | ATI_ERROR – when a recalibration cannot converge, due to |
| | LVLINIS | O | external tampering or instability, this bit will indicate the error |
| | | | and implies that the calibration does not offer optimal sensitivity. |
| | | | The PROX event in the main events register will be set along |
| | | | with this bit in such case. |
| | | 5 | CH0_ATI – An indication that a recalibration of the proximity |
| | | | sensing channel has occurred. With calibration, the PROX |
| | | | output in main events will be set and after calibration, the PROX |
| | | 4 | output will release. |
| | | 3 | QUICK RELEASE – The quick release feature is a single event |
| | | 3 | that is indicated here. This event will always imply an "ENTER |
| | | | MOV DETECT", but is not the only event that causes movement |
| | | | detection to be activated. |
| | | 2 | EXIT MOV DETECT – The user interface dictates when the |
| | | | movement channel is deactivated. The deactivation of |
| | | | movement sensing will be reported in this bit. |
| | | 1 | ENTER MOV DETECT – Movement detection is user interface |
| | | | dependant and not continually active. Movement detection implies that a separate movement channel is activated. This |
| | | | activation will be reported in this bit. |
| | | 0 | MOVEMENT – Each trigger detected by the movement |
| | | _ | algorithm is reported as an event that resets along with each |
| | | | read operation. |
| 03H | Reserved | n/a | |
| 0411 | COMMANDO | 7 | ATI CHO. Bosolibroto the provimity channel Only often station |
| 04H | COMMANDS | 7 | ATI_CH0 – Recalibrate the proximity channel. Only after closing the communications window, a recalibration of the proximity |
| L | 1 | | The communications williow, a recalibration of the proximity |





| ADDR | Register name | Bit | Description |
|-------|----------------|-----|---|
| ADDIK | -register name | | sensing electrode will be started. |
| | | 6 | DISABLE SENSING – Sensing can be disabled to save power |
| | | | or synchronize sensing in a more complex system and limit |
| | | | certain signals from affecting the measurement. |
| | | 5 | ENABLE SENSING – Sensing can be enabled at strategic times |
| | | | to limit interference in the sensitive measurement environment. |
| | | | ENABLE / DISABLE sensing will be reflected in the |
| | | | MAIN_EVENTS register. ENABLE sensing will result in a |
| | | | "SENSING DISABLED" and "RELEASE" bit being set |
| | | | simultaneously. |
| | | 4 | RESERVED |
| | | 3 | 112021112 |
| | | 2 | |
| | | 1 | AUTO ATI toggle on/off |
| | | 0 | SWITCH TO STANDALONE – Triggers a user interface restart |
| | | | in standalone (GPIO) mode while keeping all register changes |
| | | | made. Sending the command will execute as soon as the |
| | | | communications window is closed. |
| 05H | OTP Bank 1 | 7 | Standalone / I ² C mode selection including I ² C address options |
| | | 6 | (see OTP bank definition) |
| | | | *To switch to standalone mode directly from I ² C mode |
| | | | This powerful feature enables the designer to configure the |
| | | | device in I ² C mode and thereafter reduce the I ² C overhead and |
| | | | related EMI by switching to standalone for runtime. The actual |
| | | | mode switch occurs as soon as the communications window is |
| | | | closed with a stop command. |
| | | | It is recommended to enable the failsafe heartbeat when going |
| | | | from I ² C mode to standalone. The absence of the heartbeat |
| | | | should be used to indicate an unexpected reset event, implying |
| | | | the need for I ² C reconfiguration. |
| | | 5 | Proximity Threshold (low/high) read only |
| | | 4 | For reading OTP setting only. Note that the actual proximity |
| | | 2 | threshold is defined in register 0x0B. |
| | | 3 | AC Filter (see OTP bank definition) |
| | | 2 | Tough throshold (road only) |
| | | 1 | Touch threshold (read only) For reading OTP setting only. Note that the actual touch |
| | | 0 | threshold is defined in register 0x0A. |
| 06H | OTP Bank 2 | 7 | Increase debounce (see OTP bank definition) |
| 0011 | OTT Dalik Z | 6 | Target (see OTP bank definition) |
| | | 5 | Base value (see OTP bank definition) |
| | | 4 | Page value (See OTT Datik delitition) |
| | | 3 | Failsafe (see OTP bank definition) |
| | | 2 | Quick release (see OTP bank definition) |
| | | 1 | User interface (see OTP bank definition) |
| | | 0 | Osor interface (see OTT ballk delilition) |
| 07H | OTP Bank 3 | 7 | Charge transfer frequency |
| 0/11 | OTT Datik 3 | 6 | Charge transfer frequency |
| | | 5 | Advanced temperature compensation (see OTP bank definition) |
| | | 4 | IO2 function (see OTP bank definition) |
| | | 3 | 102 Tariblion (See Off Dalik delilillion) |
| | | 2 | ATI events on IO1 (see OTP bank definition) |
| | | 1 | Sample rate (see OTP bank definition) |
| | | 0 | |
| | | U | |





| ADDR | Register name | Bit | Description |
|------|----------------|--------|--|
| 08H | QUICK | 7 | The OTP options for quick release (see Quick release threshold |
| | RELEASE | 6 | in OTP Bank 0) is extended in I ² C mode to enable a very |
| | | 5 | specific release characteristic. |
| | | 4 | Quick release threshold look-up table: |
| | | | 0x0 = 150 counts |
| | | | 0x1 = 100 |
| | | | 0x2 = 50 |
| | | | 0x3 = 250 |
| | | | 0x4 = 10 |
| | | | 0x5 = 20 |
| | | | 0x6 = 25 |
| | | | 0x7 = 30 |
| | | | 0x8 = 75 |
| | | | 0x9 = 200 |
| | | | 0xA = 300 |
| | | | 0xB = 400 |
| | | | 0xC = 245 0xD = 230 |
| | | | 0xD = 230 $0xE = 335$ |
| | | | 0xE = 333 0xF = 500 |
| | | 3 | Quick release beta – This beta value is an indication of the filter |
| | | 2 | strength used to track the characteristic of the release signal. |
| | | 1 | The faster the tracking, the less likely the release will be |
| | | 0 | detected (only very quick events will be detected). The slower |
| | | | the tracking, the more likely the quick release occur (quick |
| | | | events and slow events will be detected as a quick release) |
| | | | Practical values for the beta range between: |
| | | | 0 (fast events only) and |
| | | | 4 (fast and slow events) |
| | | | The maximum of 0xF is impractical and high values are not |
| | | | recommended. |
| 2011 | 140) (E14E1) T | _ | MOVEMENT TIME OUT D |
| 09H | MOVEMENT | 7 | MOVEMENT TIME-OUT – Depending on the user interface, a |
| | | 6 | movement detection channel may be started along with specific |
| | | 5 4 | events (proximity / quick release). The timer is set and cleared as mentioned in Movement time- |
| | | 4 | out (OTP Bank 0). |
| | | | No movement time-out value: |
| | | | 0x0 = 0s |
| | | | 0x1 = 0.5s |
| | | | 0x2 = 1s |
| | | | 0x3 = 2s |
| | | | 0x4 = 4s |
| | | | 0x5 = 5s |
| | | | 0x6 = 10s |
| | | | 0x7 = 20s |
| | | | 0x8 = 30s |
| | | | 0x9 = 1min |
| | | | 0xA = 2min |
| | | | 0xB = 5min |
| | | | 0xC = 10min |
| | | | 0xD = 30min |
| | | | 0xE = 60min |
| | | 2 | 0xF = 90min |
| | | 3 | MOVEMENT THRESHOLD. |





| ADDR | Register name | Bit | Description |
|---------|-----------------|-----|---|
| - ABBIT | rtogiotor name | 2 | Movement threshold = (Value × 2) |
| | | 1 | Available range: 0 – 30 |
| | | 0 | For description see Movement threshold in OTP Bank 0. |
| | | | Note that the movement threshold in OTP Bank 1 is loaded in |
| | | | this register at start up and the OTP setting becomes read only. |
| | | | All movement threshold adjustments are performed in this |
| | | | register. 0 will cause movement to always trigger. |
| 0AH | TOUCH | n/a | Touch threshold = (Value × 4) + 4 |
| | THRESHOLD | , | Available range: 4 – 1024 |
| | | | For details on the touch threshold operation and uses see |
| | | | Touch threshold in OTP Bank 1. |
| | | | Note that the touch threshold in OTP Bank 1 is loaded in this |
| | | | register at start up and the OTP setting becomes read only. All |
| | | | touch threshold adjustments are performed in this register. |
| 0BH | PROXIMITY | 7 | , |
| | THRESHOLD | 6 | |
| | | 5 | |
| | | 4 | Reserved |
| | | 3 | |
| | | 2 | |
| | | 1 | Proximity threshold |
| | | 0 | Available range: 4 – 10 (IO2 low / I ² C mode) |
| | | | Available range: 8 – 14 (IO2 high) |
| | | | For details on the proximity threshold operation and uses see |
| | | | Proximity Threshold (low/high) in OTP Bank 1. |
| | | | Note that the proximity threshold in OTP Bank 1 is loaded in this |
| | | | register at start up and the OTP setting becomes read only. All |
| | | | runtime proximity threshold adjustments are performed in this |
| | | | register. |
| 0CH | Temperature & | n/a | 0 – 255 |
| | interference | | Default 3. Low values are recommended for intended effect. |
| | tracking | | Use a higher value when using the feature in a noisy |
| | threshold | | environment. |
| 0DH | CH0 Multipliers | 7 | Reserved |
| | | 6 | 110001100 |
| | | 5 | CH0 Sensitivity Multiplier (Values: 0 – 3) |
| | | 4 | On to Ocholity ty tytulupilor (values. 0 – 0) |
| | | 3 | |
| | | 2 | CH0 Compensation multiplier (Values: 0 – 15) |
| | | 1 | |
| | | 0 | |
| 0EH | CH0 | n/a | 0 – 255 |
| | Compensation | | 0 200 |
| 0FH | CH1 Multipliers | 7 | Reserved |
| | | 6 | 1,0001700 |
| | | 5 | CH1 Sensitivity Multiplier (Values: 0 – 3) |
| | | 4 | OTT OSTISITIVITY INICIALIDATE (VALUES: 0 - 0) |
| | | 3 | |
| | | 2 | CH1 Compensation multiplier (Values: 0 – 15) |
| | | 1 | |
| | | 0 | |
| 10H | CH1 | n/a | 0 – 255 |
| | Compensation | | |
| 11H | System flags | 7 | I ² C mode active bit |





| ADDR | Register name | Bit | Description |
|------------|------------------------|--------|---|
| AUUK | Register name | 6 | Advanced temperature tracking active |
| | | | CH1 ACTIVE – Indicates if the movement channel (CH1) is |
| | | 5 | activated |
| | | 4 | RESERVED |
| | | 3 | NO SYNC – no sync input active bit |
| | | | CH0 LTA HALTED – Indicates that some proximity shift has |
| | | | been detected according to the threshold in register 0x05 bit 7. |
| | | 2 | This event automatically clears if a proximity is not detected |
| | | | within t _{filter halt} |
| | | | ATI MODE – Indicates that CH0 or CH1 is busy with the |
| | | 1 | recalibration routine. Read the ATI in flags in register 0x13 for |
| | | | more information |
| | | | ZOOM MODE – At each threshold of the proximity channel |
| | | 0 | (proximity & touch threshold), a signal "debounce" is done |
| | | | rapidly. During this rapid event, this bit will be set. |
| 12H | UI flags | 7 | |
| | | 6 | Reserved |
| | | 5 | |
| | | 4 | Auto-ATI off bit |
| | | 3 | Sensing disabled indication bit |
| | | 2 | Quick release – Indicates when a quick release action has been |
| | | | detected |
| | | 1 | Reserved |
| | | 0 | Output active – Indicates an active proximity detection |
| 13H | ATI flags | n/a | Reserved |
| 14H | Event flags | | CH1_ATI ERROR – This will indicate that the movement |
| | | _ | channel is not operating under optimal sensitivity and the |
| | | 7 | calibration will automatically be redone in t _{redoATI} . The count- |
| | | | down time until next attempt can be read in register 0x25 and |
| | | 6 | 0x26. |
| | | 6 5 | Reserved |
| | | 4 | CH1 MOVEMENT |
| | | 7 | CH0_ATI ERROR – Because of external interference, strong |
| | | | EMI or extreme capacitive load conditions the calibration will not |
| | | | be able to reach the target sensitivity (target count – as defined |
| | | 3 | in register 0x06 bit 6). The proximity output will be set in such |
| | | | case in order to fail towards the safe side. The calibration will |
| | | | automatically be redone in t _{redoATI} . The count-down time until |
| | | | next attempt can be read in register 0x23 and 0x24. |
| | | 2 | CH0 UNDEBOUNCED – An indication that a proximity event |
| | | | has been detected before a debounce operation has been done. |
| | | 1 | CH0_ TOUCH – The touch event is flagged here for the |
| | | ' | duration of the touch |
| | | 0 | CH0_PROX – The proximity event is flagged here for the |
| | | | duration of the proximity |
| 15H | CH0 ACF_H | n/a | Proximity channel: Filtered count value |
| 16H | CH0 ACF_L | | 0 – 2000 |
| | | | This count value is related to an offset actual capacitive load. |
| | | | The offset is done though calibration and ensures system |
| 4711 | CHOLTA | r /- | Sensitivity. |
| 17H | CHOLTA I | n/a | Proximity channel: Reference count value (Long term average) 0 – 2000 |
| 18H 19H | CH0 LTA_L CH0 QRD H | n/o | |
| IBH | CU0 MKD_H | n/a | Proximity channel: Quick release detect reference value |





| ADDR | Register name | Bit | Description |
|------|---------------|-----|---|
| 1AH | CH0 QRD_L | | 0 – 2000 |
| 1BH | CH1 ACF_H | n/a | Movement channel: Filtered count value |
| 1CH | CH1 ACF_L | | 0 – 2000 |
| 1DH | CH1 UMOV_H | n/a | Movement channel: Upper reference count value |
| 1EH | CH1 UMOV_L | | 0 – 2000 |
| 1FH | CH1 LMOV_H | n/a | Movement channel: Lower reference count value |
| 20H | CH1 LMOV L | | 0 – 2000 |





12 Specifications

12.1 Absolute maximum ratings

Absolute maximum parameters specified for the device:

Exceeding these maximum specifications may cause damage to the device.

Operating temperature -20°C to 85°C

Supply Voltage (VDDHI – VSS)
 3.6V

Maximum pin voltage
 VDDHI + 0.5V (may not)

exceed VDDHI max)

Maximum continuous current (for specific Pins)
 10mA

Minimum pin voltage
 VSS – 0.5V

Minimum power-on slope 100V/s

ESD protection ±8kV (Human body model)

Package Moisture Sensitivity Level (MSL)
 1 (DFN-10, TSOT23-6 & WLCSP-8)



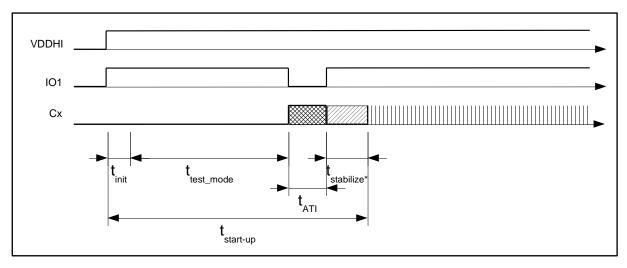


Table 12.1 IQS231A General Operating Conditions

| DESCRIPTION | Conditions | PARAME TER | MIN | TYP | MAX | UNIT |
|---------------------------|--|---------------------------|------|------|------|------|
| Supply voltage | | V_{DDHI} | 1.75 | n/a | 3.6 | V |
| Internal regulator output | $\begin{array}{ccc} 1.75 & \leq & V_{DDHI} \leq \\ 3.6 & & & & \\ \end{array}$ | V_{REG} | 1.62 | 1.65 | 1.72 | V |
| Default Operating Current | 3.3V, Scan time = 30ms | I _{IQS231ALP30} | | 33 | | μΑ |
| Full Power Setting | 3.3V, Scan time =9ms | I _{IQS231AFP} | | 80 | | μА |
| Low Power Setting 1 | 3.3V, Scan time =128ms | I _{IQS231ALP128} | | 7.5 | | μА |
| Low Power Setting 2 | 3.3V, Scan time =256ms | I _{IQS231ALP256} | | 5 | | μА |
| Halt charge | | | | 1 | | uA |

Table 12.2 Start-up and shut-down slope Characteristics

| DESCRIPTION | Conditions | PARAMETER | MIN | MAX | UNIT |
|---------------------------|---|------------|-----|-----|------|
| Power On Reset | V _{DDHI} Slope ≥ 100V/s @25°C | POR | 1.0 | 1.6 | V |
| Brown Out Detect | | BOD avoid | n/a | 1.5 | V |
| Brown Out Detect (Ensure) | V _{DDHI} Slope ≥ 100V/s @25°C | BOD ensure | 1.0 | n/a | V |



^{*}Proximity or touches made during $t_{\text{stabilize}}$ will not be recognized but rather be part of the calibration.

Figure 12.1 Timing specification during power-on



Table 12.3 Various IQS231A characteristics

| DESCRIPTION | MIN | TYP | MAX | UNIT |
|--|------|------|-----|------|
| t _{init} | | 15 | | ms |
| t _{test_mode} | | 340 | | ms |
| t _{sensing_inactive} 30Hz – default | 396 | | 436 | ms |
| t _{ATI} | 41 | 41 | 81 | ms |
| t _{stabilize} 30Hz – default | | 340 | | ms |
| t _{stabilize 100Hz} | | 128 | | ms |
| t _{stabilize 8Hz} | | 1192 | | ms |
| t _{stabilize 4Hz} | | 2344 | | ms |
| t _{comms_timeout} | - | 20 | - | ms |
| t _{failsafe} | | 500 | | us |
| t _{CLK_stretch} | | 5 | | ms |
| t _{filter_halt} | | 5 | | S |
| $t_{redoATI}$ | | 10 | | S |
| t _{awake} | | 9 | | ms |
| R _{internal} | | 20 | | kΩ |
| R _{I2C_series} | | | 100 | Ω |
| f _{sampling} | 16.5 | 500 | 500 | kHz |

Table 12.4 Digital input trigger levels

| DESCRIPTION | Conditions | PARAMETER | MIN | TYPICAL | MAX | UNIT |
|--------------------|--------------|--------------------------|------|---------|------|------|
| All digital inputs | VDDHI = 3.3V | Input low level voltage | 1.19 | 1.3 | 1.3 | V |
| All digital inputs | VDDHI = 1.8V | Input low level voltage | 0.54 | 0.6 | 0.76 | V |
| All digital inputs | VDDHI = 1.8V | Input high level voltage | 0.9 | 1.0 | 1.2 | V |
| All digital inputs | VDDHI = 3.3V | Input high level voltage | 1.90 | 2.1 | 2.20 | V |

Table 12.5 Digital output levels

| DESCRIPTION | Conditions | PARAMETER | @1mA* | @10mA* | UNIT |
|---------------------|--------------|-----------------|-------|--------|------|
| Output voltage low | VDDHI = 3.3V | V _{OL} | 0.01 | 0.1 | V |
| Output voltage high | VDDHI = 3.3V | V _{OH} | n/a** | n/a** | V |

^{*} Current sinked into output pin

^{**} Only open drain output offered. Pull-up resistor to VDD recommended





13 Package information

The device is available in three packages: TSOT23-6, DFN-10 & WLCSP-8.

13.1 TSOT23-6

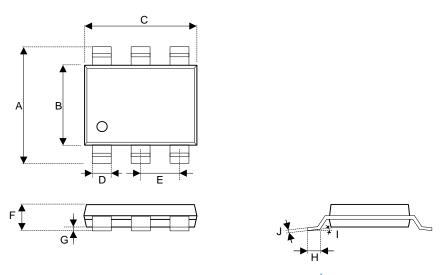


Figure 13.1 TSOT23-6 Packagingⁱ

Table 13.1 TSOT23-6 Dimensions

| Dimension | Min (mm) | Max (mm) | |
|-----------|------------|----------|--|
| Α | 2.60 | 3.00 | |
| В | 1.50 | 1.70 | |
| С | 2.80 | 3.00 | |
| D | 0.30 | 0.50 | |
| Е | 0.95 Basic | | |
| F | 0.84 | 1.00 | |
| G | 0.00 | 0.10 | |
| Н | 0.30 | 0.50 | |
| 1 | 0° | 8° | |
| J | 0.03 | 0.20 | |

ⁱ Drawing not on Scale





13.2 DFN-10

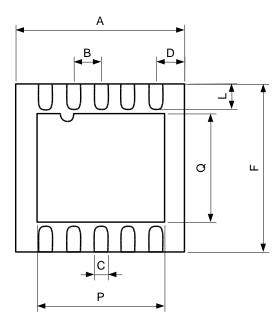


Figure 13.2 DFN-10 Package dimensions (bottom view)
Table 13.2 DFN-10 Package dimensions (bottom)

| Dimension | [mm] | |
|-----------|--------|--|
| А | 3 ±0.1 | |
| В | 0.5 | |
| С | 0.25 | |
| D | n/a | |
| F | 3 ±0.1 | |
| L | 0.4 | |
| Р | 2.4 | |
| Q | 1.65 | |

Table 13.3 DFN-10 Package dimensions (side)

| Dimension | [mm] | |
|-----------|---------|--|
| G | 0.05 | |
| Н | 0.65 | |
| I | 0.7-0.8 | |





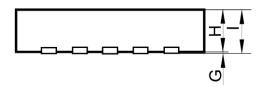


Figure 13.3 DFN-10 Package dimensions (side)

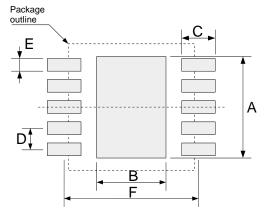


Figure 13.4 Recommended DFN-10 Landing dimensions

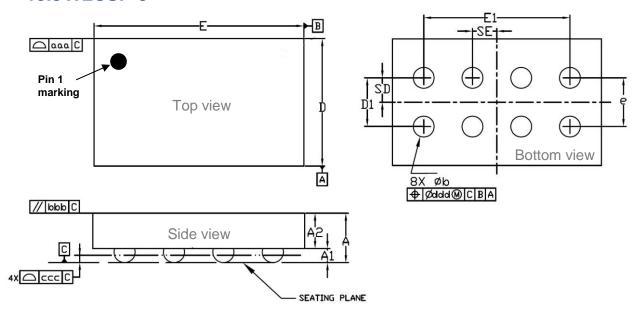
Table 13.4 DFN-10 Landing dimensions

| Dimension | [mm] |
|-----------|------|
| А | 2.4 |
| В | 1.65 |
| С | 0.8 |
| D | 0.5 |
| Е | 0.3 |
| F | 3.2 |





13.3 WLCSP-8



| Dimensional Ref. | | | | | |
|------------------|-----------|---------|--------|--|--|
| REF. | Min. | Nom. | Max. | | |
| Α | 0.310 | 0.350 | 0.390 | | |
| Α1 | 0.085 | 0.100 | 0.115 | | |
| Α2 | 0.225 | 0.250 | 0.275 | | |
| D | 0.865 | 0.880 | 0.895 | | |
| Е | 1.455 | 1.470 | 1.485 | | |
| D1 | 0.300 | 0.350 | 0.400 | | |
| E1 | 1.000 | 1.050 | 1.100 | | |
| Ь | 0.125 | 0.150 | 0.175 | | |
| е | 0 | .350 BS | C | | |
| SD | 0 | .175 BS | C | | |
| SE | 0 | .175 BS | C | | |
| To | ol. of Fo | rm&Pos | sition | | |
| ааа | 0.10 | | | | |
| ЬЬЬ | 0.10 | | | | |
| CCC | 0.05 | | | | |
| ddd | | 0.05 | | | |

Figure 13.5 IQS231A WLCSP-8 dimensions (in mm)

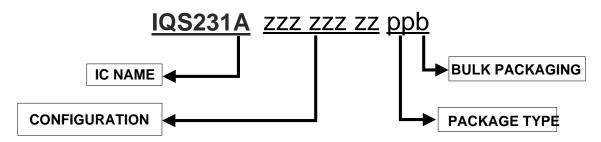




14 Ordering and Part-number Information

14.1 Ordering Information

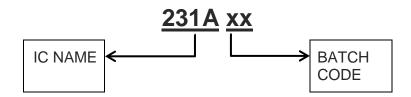
Please check stock availability with your local distributor.



| CONFIGURATION | ZZZ ZZZ ZZ | = | IC configuration (hexadecimal) | |
|----------------|------------|---|---|--|
| | | | Default 000 000 00 (other configurations | |
| | | | available on special request) | |
| PACKAGE TYPE | DN | = | DFN(3x3)-10 | |
| | TS | = | TSOT23-6 package | |
| | CS | = | WLCSP-8 package | |
| BULK PACKAGING | R | = | Reel (3000pcs/reel) – MOQ = 3000pcs | |
| | | | MOQ = 1 reel (orders shipped as full reels) | |

14.2 Device Numbering Convention - TSOT23-6

14.2.1 Top



| IC NAME | 231A | = | IQS231A |
|------------|------|---|----------|
| Batch Code | XX | = | AA to ZZ |

14.2.2 Bottom

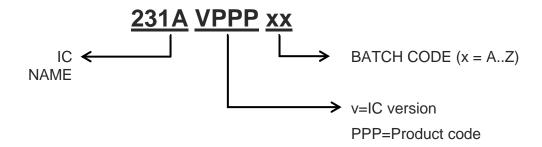






14.3 Device numbering convention: 8-pin WLCSP

14.3.1 Top



14.3.2 Bottom

No marking present

14.4 Device Numbering Convention – DFN10



| DEVICE NAME | Α | = | IQS231A |
|-------------------|---|---|-----------------------|
| REVISION | В | = | v (IC Version Number) |
| TEMPERATURE RANGE | С | = | t (-20°C to 85°C) |
| DATE CODE | D | = | p (Internal use) |
| | Е | = | wwyy (Batch number) |
| PIN 1 MARKING | F | = | Dot to indicate pin 1 |





15 Revision History

| Revision Number | Description | Date of issue |
|-----------------|---|---------------------|
| v1.0 | IC release version | 16 March 2016 |
| V1.1 | TSOT23-6 package added BOD and POR values updated | 18 July 2016 |
| V1.2 | Reference schematic updated. Component selection guide also included | 8 September 2016 |
| V1.3 | Introduction added to first page Start-up and ATI time description added | 13 December 2016 |
| V1.4 | Switch from I2C to standalone mode information updated | 10 February 2017 |
| V1.5 | WLCSP package information added | 13 March 2017 |
| V1.6 | Proximity threshold options in I ² C mode corrected Commands updated to include "Auto ATI on/off" Temperature compensation feature renamed to include the detection of radiated and conducted interference "I2C and sensing timing" section added. Schematics updated with recommended components. | 18 July 2017 |
| V1.7 | Movement threshold option in I ² C mode errata Capacitive resolution and load capability added to introduction page WLCSP package pin 5 recommendation | 4 September 2017 |
| V1.8 | Added functional block diagram with basic function descriptions Added warning to section 4 OTP table when using the most sensitive settings. Updated and added AC filter information to section 10.2 Added section 9.8 & 9.9 with timing accuracy information Bottom marking changes for new device versions: see product change notices IQS231A minimum temperature has changed from -40°C to -20°C | 10 November 2017 |





Appendix A Contact Information

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Please visit www.azoteg.com for a list of distributors and worldwide representation.

The following patents relate to the device or usage of the device: US 6,249,089 B1; US 6,621,225 B2; US 6,650,066 B2; US 6,952,084 B2; US 6,984,900 B1; US 7,084,526 B2; US 7,084,531 B2; US 7,265,494 B2; US 7,291,940 B2; US 7,329,970 B2; US 7,336,037 B2; US 7,443,101 B2; US 7,466,040 B2; US 7,498,749 B2; US 7,528,508 B2; US 7,755,219 B2; US 7,772,781 B2; US 7,781,980 B2; US 7,915,765 B2; US 7,994,726 B2; US 8,035,623 B2; US RE43,606 E; US 8,288,952 B2; US 8,395,395 B2; US 8,531,120 B2; US 8,659,306 B2; US 8,823,273 B2; EP 1 120 018 B2; EP 1 206 168 B1; EP 1 308 913 B1; EP 1 530 178 A1; EP 2 351 220 B1; EP 2 559 164 B1; CN 1330853; CN 1783573; AUS 761094; HK 104 1401

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